

ESA Technology HMI

Contact Information

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Supported Protocols

Use one of the following protocol/drivers to interface an ESA HMI to a QCI servo controller.

- Modbus RTU (see our website for application note “QCI-AN038 Modbus Protocol”).
- Modbus TCP (see our website for application note “QCI-AN028 Modbus TCP”).

The above protocols allow the HMI to read and write to our registers. The HMI’s variables are thus mapped to our registers. See the above application notes for examples.